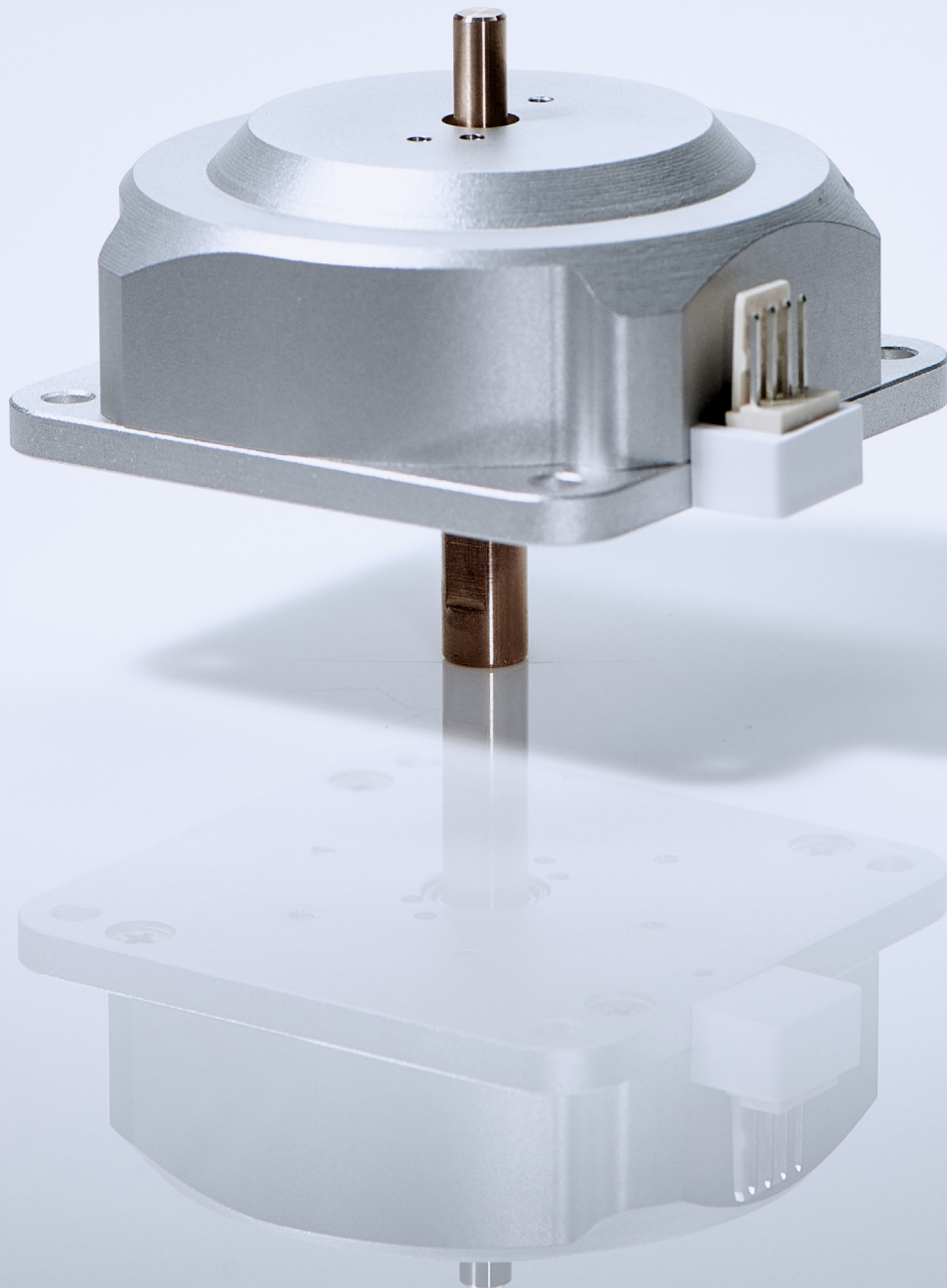
A detailed close-up photograph of a piezo sonic motor. The central feature is a polished metal shaft with a threaded section. This shaft is surrounded by a circular metal housing with several small holes. The housing is secured by several gold-colored screws. The outermost part of the assembly shows a series of copper-colored, rectangular segments arranged in a ring, likely part of the motor's stator or a cooling system. The lighting is dramatic, highlighting the metallic textures and the precision of the engineering.

PIEZO SONIC MOTOR

Product catalog

Piezosonic Motor

Small size, high torque, posture can be maintained with zero power, and can be used in a magnetic field environment.



A big energy from a small body

Piezosonic motor engineers who have been researching and developing for more than 20 years have been working on solving two contradictory problems of ultrasonic motors such as longer life and higher torque.

As a result, we succeeded in prolonging the life as compared with conventional ultrasonic motors. In addition, the technology received a prize from [The Japan Society for Precision Engineering] that is academic societies in Japan. (Patent pending)

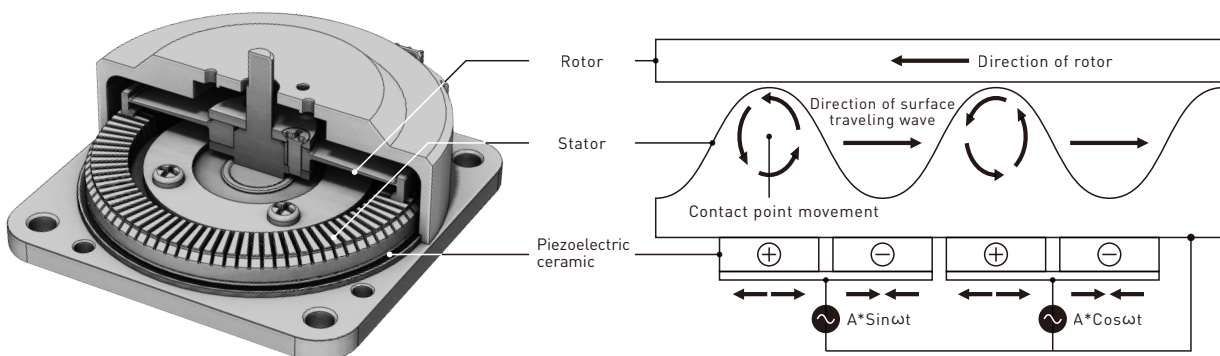
We are developing ultrasonic motors suitable for stages for semiconductor manufacturing equipment requiring high precision, nonmagnetic and high torque, and various positioning devices.

And, because we have the circuit technology of ultrasonic motor which is difficult to configure, we are developing a driver with a drive circuit with excellent response and control characteristics.

PIEZO SONIC MOTOR

What is Piezosonic Motor?

Piezosonic motors do not use magnets and coils. The driving energy is the vibration of piezoelectric ceramic. Because it rotates by using friction, it is small and lightweight. The torque is 5 to 10 times that of a DC motor of the same size. Since it does not use coils and magnets for the drive source, it can construct a nonmagnetic motor, and it can be used with confidence in a semiconductor manufacturing equipment or the like which is unlikely to be affected by high magnetic field in MRI and magnetic field. In addition, it is possible to maintain posture with non-energized or non-control signals. And because there is no backlash, highly accurate position control by direct drive of the device is possible. It is also highly responsive to start and stop signals. Our ultrasonic motor is suitable for transport equipment such as stage, camera cloud stand, gimbal, indexing device and articulated robot joint motor.



Comparison with other types

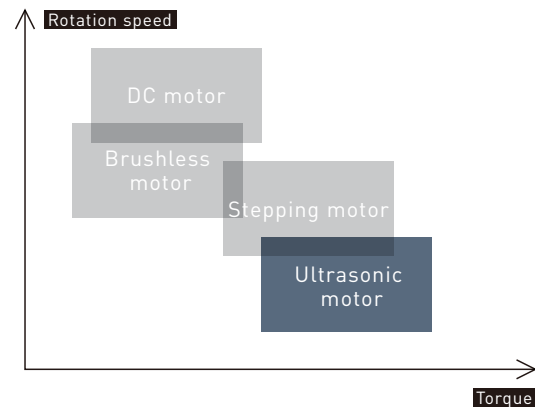
Even though it is small and quiet, precise positioning with high torque is possible.

Rotation speed · Torque

This figure focuses on the relationship between the torque and the rotation speed of the same size Ultrasonic motor, DC motor, Brushless motor, Stepping motor.

The ultrasonic motor has characteristics of Low speed and High torque compared with other motors.

Because of the frictional force it can maintain high holding force even when it is not controlled and there is no backlash. So you can construct a direct drive actuator system that does not use gears.



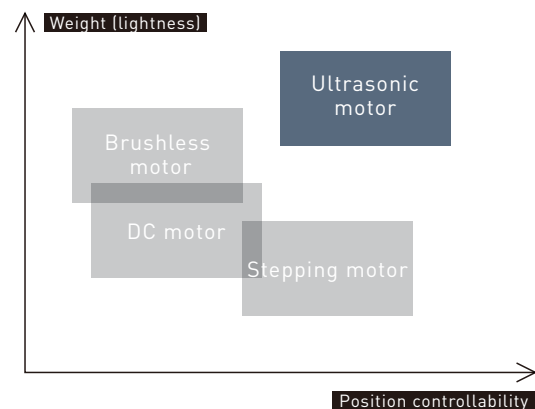
Weight · Position control

This figure focuses on the relationship between position controllability and weight (lightness) of the same sized Ultrasonic motor, DC motor, Brushless motor, and Stepping motor.

The ultrasonic motor has a feature that it is lighter and has higher position controllability than other motors.

Since the weight of the rotating part is light, the inertia is small, and when the driving signal stops it will stop by the frictional force quickly, so precise positioning is possible.

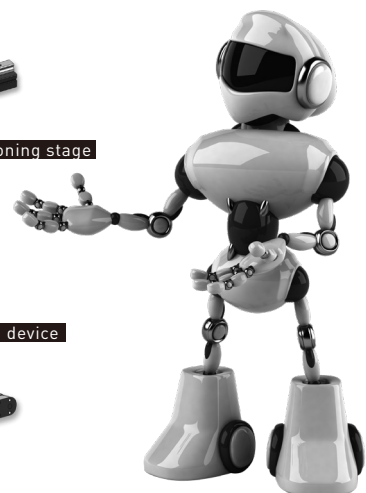
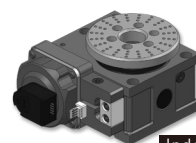
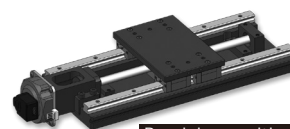
※The final positioning accuracy depends on external sensors (encoder, potentiometer and control controller).



Application example of Ultrasonic motor

Transport systems for general and magnetic environments, robot actuators

- Compact transport device usable in office etc.
- Small sorting and dispensing equipment available in offices, etc.
- Silent moving device for monitoring camera
- Gimbal device for attitude control
- Motors for transport and drive in medical equipment CT and MRI
- Robot arm capable of fine control
- Motor for driving in a strong radiation environment
- Motor for vacuum environment (space environment etc.)

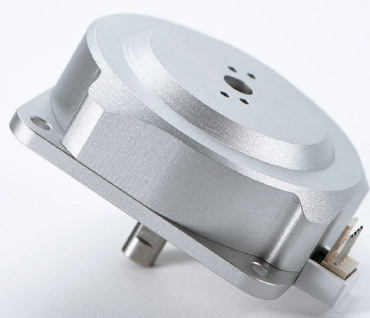


Motor for general environment

PSM60S SERIES

APPEARANCE / FEATURES

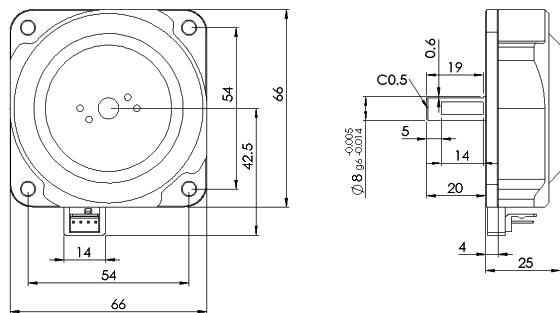
PSM60S-A



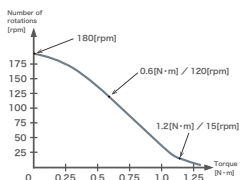
Sensorless single-shaft motor for general environment.

The minimum size in PSM 60S series.

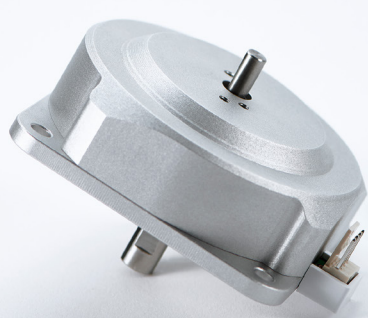
It is suitable for positioning using a sensor mounted on the device or as an intermittent same action motor with a timer.



Model Name	Single-shaft motor	PSM60S-A
Drive Frequency	40~45 [KHz]	
Drive Voltage	130 [Vrms]	
Rated Speed	120 [rpm]	
Maximum Speed	180 [rpm]	
Rated Torque	0.6 [N·m]	
Maximum Torque	1.2 [N·m]	
Holding Torque	1.2 [N·m]	
Direction & Response	CW, CCW, Less than 1 [ms] [No-load]	
Temperature Range	-10 ~ +55 [°C]	
Life Time	3,000 [Hours]	
Size(W×D×H)	66×66×45 [mm]	
Weight	230 [g]	
Encoder resolution	Without encoder, single-shaft	
Minimum Accuracy	Depends on external sensor	

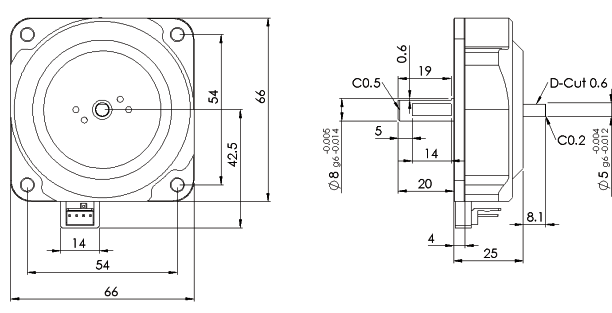


PSM60S-B

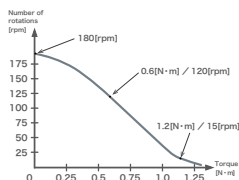


Sensorless double-shaft motor for general environment.

It has a sub shaft for directly attaching external sensors made by other companies to the motor. Control using the encoder and tacho generator becomes possible.



Model Name	Double-shaft motor	PSM60S-B
Drive Frequency	40~45 [KHz]	
Drive Voltage	130 [Vrms]	
Rated Speed	120 [rpm]	
Maximum Speed	180 [rpm]	
Rated Torque	0.6 [N·m]	
Maximum Torque	1.2 [N·m]	
Holding Torque	1.2 [N·m]	
Direction & Response	CW, CCW, CW, CCW, Less than 1 [ms] [No-load]	
Temperature Range	-10 ~ +55 [°C]	
Life Time	3,000 [Hours]	
Size(W×D×H)	66×66×53 [mm]	
Weight	233 [g]	
Encoder resolution	Without encoder, double-shaft	
Minimum Accuracy	Depends on external sensor	



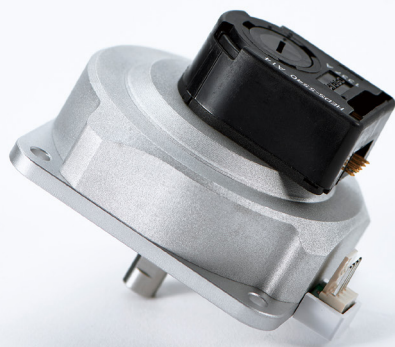
DESIGN

SPEC

Motor for general environment

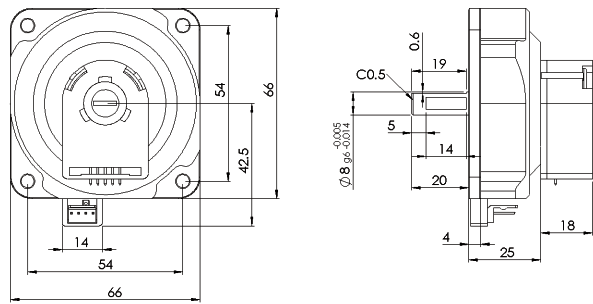
PSM60S SERIES

PSM60S-E

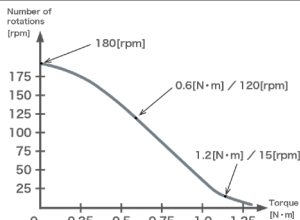


Motor with 500 p/r encoder for general environment. Equipped with 500 pulse/turn TTL signals output encoder.

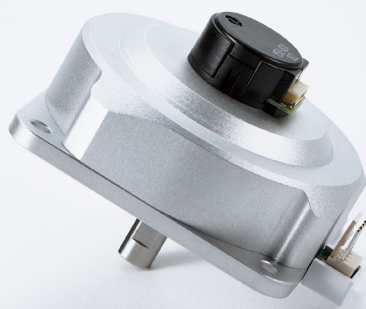
Motor position and speed can be controlled with accuracy of $\pm 0.18^\circ$ (Multiplying by 4 times). It is ideal as a motor for transfer equipment using ball screws.



Model Name	Motor with 500 p/r encoder PSM60S-E
Drive Frequency	40~45 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	120 [rpm]
Maximum Speed	180 [rpm]
Rated Torque	0.6 [N·m]
Maximum Torque	1.2 [N·m]
Holding Torque	1.2 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×63 [mm]
Weight	250 [g]
Encoder resolution	500 [p/r]
Minimum Accuracy	0.18°

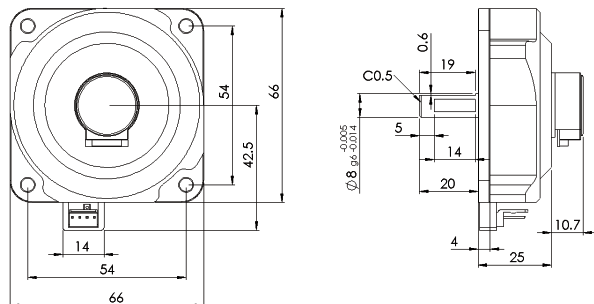


PSM60S-ET

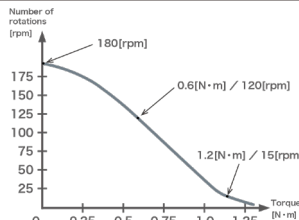


Motor with 1,000 p/r encoder for general environment. Equipped with 1,000 pulse/turn TTL signals output encoder.

Motor position and speed can be controlled with accuracy of $\pm 0.09^\circ$ (Multiplying by 4 times). It is ideal as a motor for transportation equipment such as high-precision positioning stages.



Model Name	Motor with 1,000 p/r encoder PSM60S-ET
Drive Frequency	40~45 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	120 [rpm]
Maximum Speed	180 [rpm]
Rated Torque	0.6 [N·m]
Maximum Torque	1.2 [N·m]
Holding Torque	1.2 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×56 [mm]
Weight	240 [g]
Encoder resolution	1,000 [p/r]
Minimum Accuracy	0.09°



APPEARANCE / FEATURES

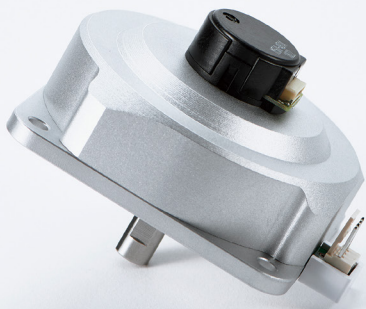
DESIGN

SPEC

Motor for general environment

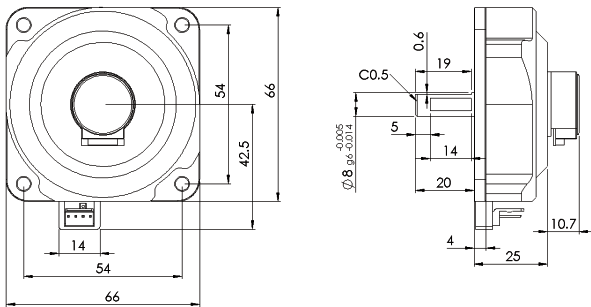
PSM60S SERIES

PSM60S-E2T

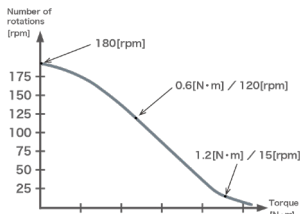


Motor with 2,000 p/r encoder for general environment. Equipped with 2,000 pulse/turn TTL signals output encoder.

Motor position and speed can be controlled with accuracy of $\pm 0.045^\circ$ (Multiplying by 4 times). It is ideal as a motor for ultra-high precision indexing equipment.



Model Name	Motor with 2,000 p/r encoder PSM60S-E2T
Drive Frequency	40~45 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	120 [rpm]
Maximum Speed	180 [rpm]
Rated Torque	0.6 [N·m]
Maximum Torque	1.2 [N·m]
Holding Torque	1.2 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×56 [mm]
Weight	240 [g]
Encoder resolution	2,000 [p/r]
Minimum Accuracy	0.045°



Motor for magnetic field environment

PSM60N SERIES

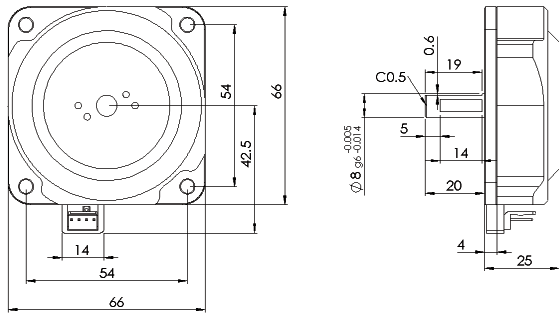
PSM60N-A



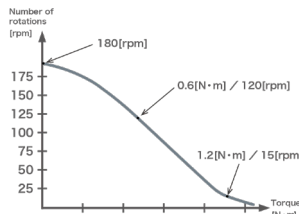
Sensorless single-shaft motor for magnetic field environment.

Applicable to 3 [T] magnetic field environment. Minimum size for PSM 60 N series.

It is ideal as a positioning and transport motor using sensors installed in devices such as MRI and elemental analyzers that are used in high-magnetic field.



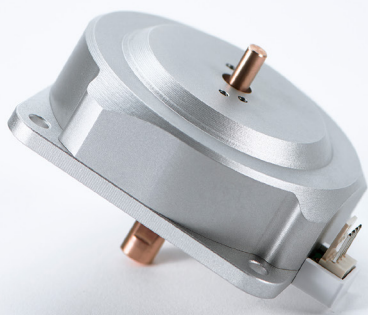
Model Name	Single-shaft motor PSM60N-A
Drive Frequency	40~45 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	120 [rpm]
Maximum Speed	180 [rpm]
Rated Torque	0.6 [N·m]
Maximum Torque	1.2 [N·m]
Holding Torque	1.2 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×45 [mm]
Weight	230 [g]
Encoder resolution	Without encoder, single-shaft
Minimum Accuracy	Depends on external sensor



Motor for magnetic field environment

PSM60N SERIES

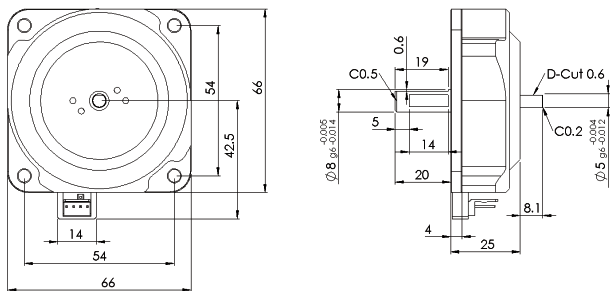
PSM60N-B



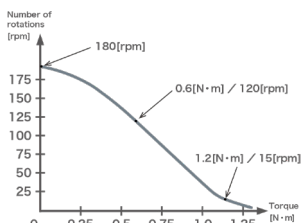
Sensorless double-shaft motor for magnetic field environment.

It has a subshaft for mounting external sensors of other manufacturers directly to the motor.

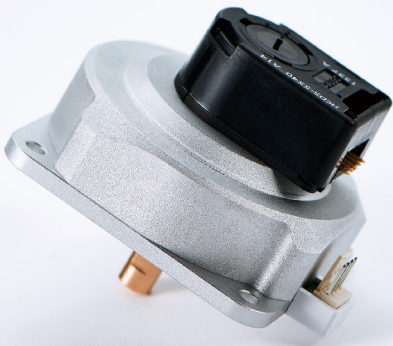
This motor can control the equipment using a third-party encoder or tachogenerator that can be used in a magnetic field.



Model Name	Double-shaft motor	PSM60N-B
Drive Frequency	40~45 [KHz]	
Drive Voltage	130 [Vrms]	
Rated Speed	120 [rpm]	
Maximum Speed	180 [rpm]	
Rated Torque	0.6 [N·m]	
Maximum Torque	1.2 [N·m]	
Holding Torque	1.2 [N·m]	
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)	
Temperature Range	-10 ~ +55 [°C]	
Life Time	3,000 [Hours]	
Size(W×D×H)	66×66×53 [mm]	
Weight	233 [g]	
Encoder resolution	Without encoder, double-shaft	
Minimum Accuracy	Depends on external sensor	



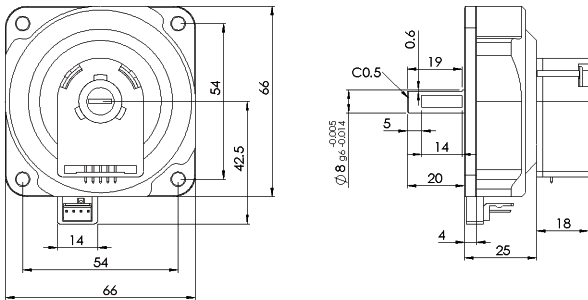
PSM60N-E



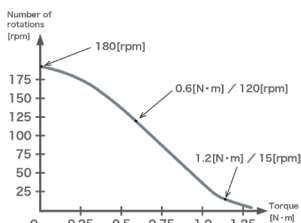
Motor with 500 p/r encoder for magnetic field environment.

Equipped with 500 pulse/turn TTL signals output encoder. Motor position and speed can be controlled with accuracy of $\pm 0.18^\circ$ (Multiplying by 4 times) in a magnetic field environment of 3 [T].

It is ideal as a motor for transfer equipment using ball screws.



Model Name	Motor with 500 p/r encoder	PSM60N-E
Drive Frequency	40~45 [KHz]	
Drive Voltage	130 [Vrms]	
Rated Speed	120 [rpm]	
Maximum Speed	180 [rpm]	
Rated Torque	0.6 [N·m]	
Maximum Torque	1.2 [N·m]	
Holding Torque	1.2 [N·m]	
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)	
Temperature Range	-10 ~ +55 [°C]	
Life Time	3,000 [Hours]	
Size(W×D×H)	66×66×63 [mm]	
Weight	250 [g]	
Encoder resolution	500 [p/r]	
Minimum Accuracy	0.18°	

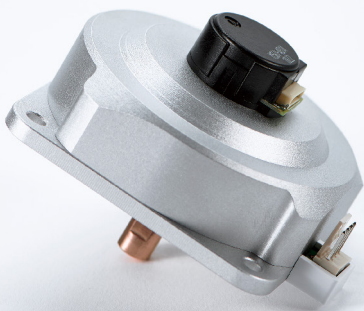


Motor for magnetic field environment

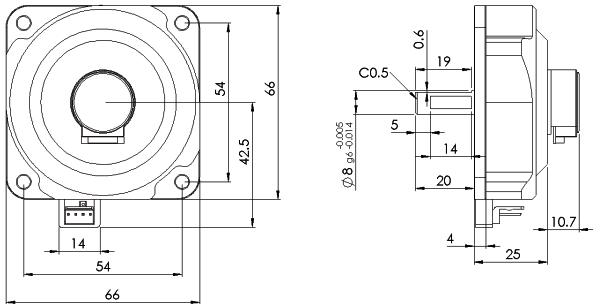
PSM60N SERIES

APPEARANCE / FEATURES

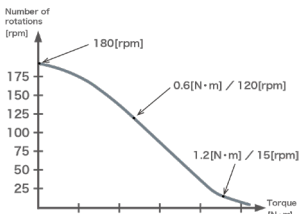
PSM60N-ET



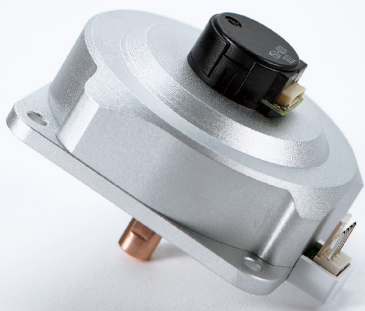
Motor with 1,000 p/r encoder for magnetic field environment.
Equipped with 1,000 pulse/trun TTL signals output encoder. Motor position and speed can be controlled with accuracy of $\pm 0.09^\circ$ (Multiplying by 4 times) in a magnetic field of 3 [T]. It is ideal as a motor for high-precision positioning stages used in MRI.



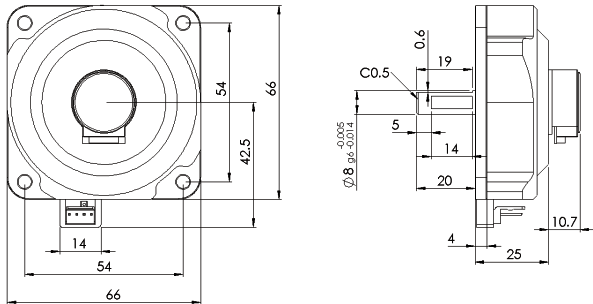
Model Name	Motor with 1,000 p/r encoder PSM60N-ET
Drive Frequency	40~45 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	120 [rpm]
Maximum Speed	180 [rpm]
Rated Torque	0.6 [N·m]
Maximum Torque	1.2 [N·m]
Holding Torque	1.2 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] [No-load]
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×56 [mm]
Weight	240 [g]
Encoder resolution	1,000 [p/r]
Minimum Accuracy	0.09°



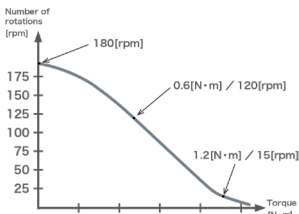
PSM60N-E2T



Motor with 2,000 p/r encoder for magnetic field environment.
Equipped with 2,000 pulse/turn TTL signals output encoder. Motor position and speed can be controlled with an accuracy of $\pm 0.045^\circ$ (Multiplying by 4 times) in a magnetic field of 3 [T]. It is ideal as a motor for ultra-high precision indexing equipment used in MRI.



Model Name	Motor with 2,000 p/r encoder PSM60N-E2T
Drive Frequency	40~45 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	120 [rpm]
Maximum Speed	180 [rpm]
Rated Torque	0.6 [N·m]
Maximum Torque	1.2 [N·m]
Holding Torque	1.2 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] [No-load]
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×56 [mm]
Weight	240 [g]
Encoder resolution	2,000 [p/r]
Minimum Accuracy	0.045°



DESIGN

SPEC

Motor for general environment

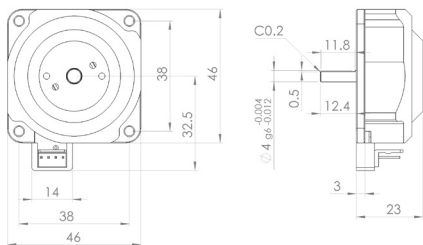
PSM40S SERIES

APPEARANCE / FEATURES

PSM40S-A



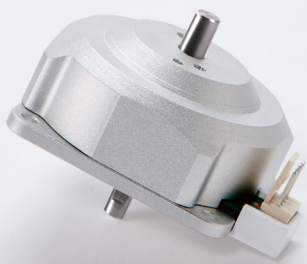
Sensorless single-shaft small motor for general environment.
The minimum size in PSM 40S series.
It is suitable for positioning using a sensor mounted on the device or as an intermittent same action motor with a timer.



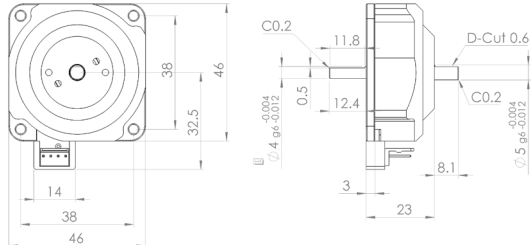
※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD Φ28 on the motor base side

Model Name	Single-shaft motor PSM40S-A
Drive Frequency	52~58 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	150[rpm]
Maximum Speed	250[rpm]
Rated Torque	0.15 [N·m]
Maximum Torque	0.3 [N·m]
Holding Torque	0.3 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	46×46×35.5 [mm]
Weight	83 [g]
Encoder resolution	Without encoder, Single-shaft
Minimum Accuracy	Depends on external sensor

PSM40S-B



Sensorless double-shaft small motor for general environment.
It has a sub shaft for directly attaching external sensors made by other companies to the motor.
Control using the encoder and tacho generator becomes possible.



※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD Φ28 on the motor base side

Model Name	Double-shaft motor PSM40S-B
Drive Frequency	52~58 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	150[rpm]
Maximum Speed	250[rpm]
Rated Torque	0.15 [N·m]
Maximum Torque	0.3 [N·m]
Holding Torque	0.3 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	46×46×43.5 [mm]
Weight	84 [g]
Encoder resolution	Without encoder, double-shaft
Minimum Accuracy	Depends on external sensor

※PSM40 series will be made to order.

DESIGN

SPEC

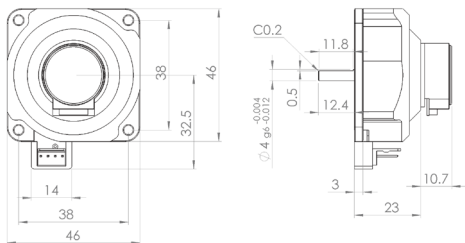
Motor for general environment

PSM40S SERIES

PSM40S-E

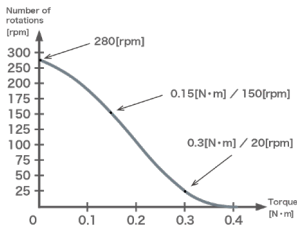


Small motor with 500 p/r encoder for general environment.
Equipped with 500 pulse/turn TTL signals output encoder. Motor position and speed can be controlled with accuracy of $\pm 0.18^\circ$ (Multiplying by 4 times). It is ideal as a motor for small transfer equipment using ball screws.

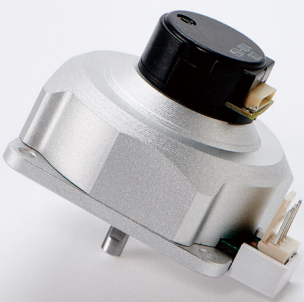


※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD $\Phi 28$ on the motor base side

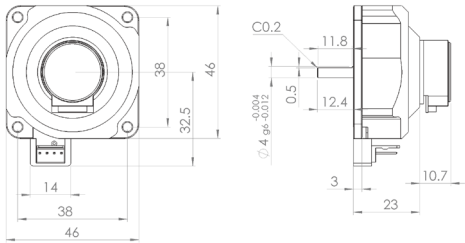
Model Name	Motor with 500 p/r encoder PSM40S-E
Drive Frequency	52~58 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	150[rpm]
Maximum Speed	250[rpm]
Rated Torque	0.15 [N·m]
Maximum Torque	0.3 [N·m]
Holding Torque	0.3 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	46×46×46 [mm]
Weight	90[g]
Encoder resolution	500 [p/r]
Minimum Accuracy	0.18°



PSM40S-ET

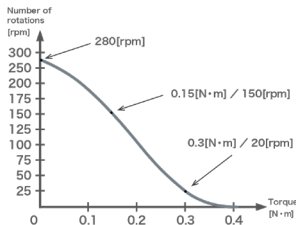


Small motor with 1,000 p/r encoder for general environment.
Equipped with 1,000 pulse/turn TTL signals output encoder. Motor position and speed can be controlled with accuracy of $\pm 0.09^\circ$ (Multiplying by 4 times). It is ideal as a motor for small transportation equipment such as high-precision positioning stages.



※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD $\Phi 28$ on the motor base side

Model Name	Motor with 1,000 p/r encoder PSM40S-ET
Drive Frequency	52~58 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	150[rpm]
Maximum Speed	250[rpm]
Rated Torque	0.15 [N·m]
Maximum Torque	0.3 [N·m]
Holding Torque	0.3 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	46×46×46 [mm]
Weight	90[g]
Encoder resolution	1,000 [p/r]
Minimum Accuracy	0.09°



※PSM40 series will be made to order.

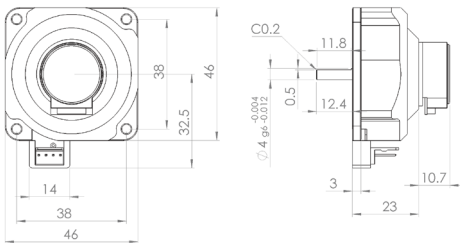
Motor for general environment

PSM40S SERIES

PSM40S-E2T



Small motor with 2,000 p/r encoder for general environment.
Equipped with 2,000 pulse/turn TTL signals output encoder.Motor position and speed can be controlled with accuracy of $\pm 0.045^\circ$ (Multiplying by 4 times).
It is ideal as a motor for ultra-high precision indexing equipment.



※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD $\Phi 28$ on the motor base side

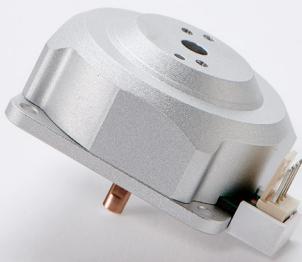
Model Name	Motor with 2,000 p/r encoder	PSM40S-E2T
Drive Frequency	52~58 [KHz]	
Drive Voltage	130 [Vrms]	
Rated Speed	150[rpm]	
Maximum Speed	250[rpm]	
Rated Torque	0.15 [N·m]	
Maximum Torque	0.3 [N·m]	
Holding Torque	0.3 [N·m]	
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)	
Temperature Range	-10 ~ +55 [°C]	
Life Time	3,000 [Hours]	
Size(W×D×H)	46×46×46 [mm]	
Weight	90[g]	
Encoder resolution	2,000[p/r]	
Minimum Accuracy	0.045°	

※PSM40 series will be made to order.

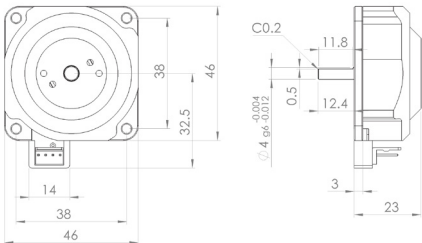
Motor for magnetic field environment

PSM40N SERIES

PSM40N-A



Sensorless single-shaft small motor for magnetic field environment.
Applicable to 3 [T] magnetic field environment.
Minimum size for PSM 60 N series.
It is ideal as a positioning and transport motor using sensors installed in devices such as MRI and elemental analyzers that are used in high-magnetic field.



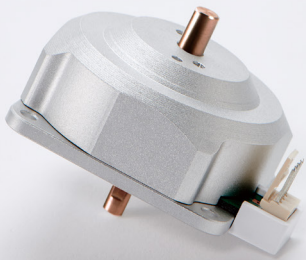
※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD $\Phi 28$ on the motor base side

Model Name	Single-shaft motor	PSM40N-A
Drive Frequency	52~58 [KHz]	
Drive Voltage	130 [Vrms]	
Rated Speed	150[rpm]	
Maximum Speed	250[rpm]	
Rated Torque	0.15 [N·m]	
Maximum Torque	0.3 [N·m]	
Holding Torque	0.3 [N·m]	
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)	
Temperature Range	-10 ~ +55 [°C]	
Life Time	3,000 [Hours]	
Size(W×D×H)	46×46×35.5 [mm]	
Weight	83 [g]	
Encoder resolution	Without encoder, Single-shaft	
Minimum Accuracy	Depends on external sensor	

Motor for magnetic field environment

PSM40N SERIES

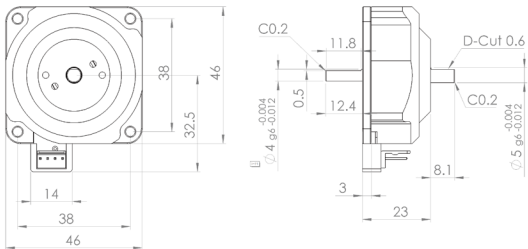
PSM40N-B



Sensorless double-shaft small motor for magnetic field environment.

It has a subshaft for mounting external sensors of other manufacturers directly to the motor.

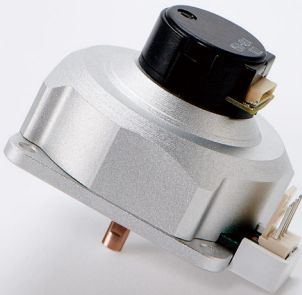
This motor can control the equipment using a third-party encoder or tacho generator that can be used in a magnetic field.



※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD Φ28 on the motor base side

Model Name	Double-shaft motor PSM40N-B
Drive Frequency	52~58 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	150[rpm]
Maximum Speed	250[rpm]
Rated Torque	0.15 [N·m]
Maximum Torque	0.3 [N·m]
Holding Torque	0.3 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	46×46×43.5 [mm]
Weight	84 [g]
Encoder resolution	Without encoder, Single-shaft
Minimum Accuracy	Depends on external sensor

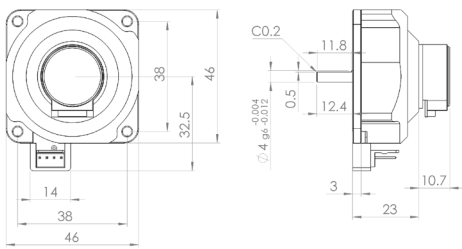
PSM40N-E



Small motor with 500 p/r encoder for magnetic field environment.

Equipped with 500 pulse/turn TTL signals output encoder. Motor position and speed can be controlled with accuracy of $\pm 0.18^\circ$ (Multiplying by 4 times) in a magnetic field environment of 3 [T].

It is ideal as a motor for small transfer equipment using ball screws.



※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD Φ28 on the motor base side

Model Name	Motor with 500 p/r encoder PSM40N-E
Drive Frequency	52~58 [KHz]
Drive Voltage	130 [Vrms]
Rated Speed	150[rpm]
Maximum Speed	250[rpm]
Rated Torque	0.15 [N·m]
Maximum Torque	0.3 [N·m]
Holding Torque	0.3 [N·m]
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	46×46×46 [mm]
Weight	90[g]
Encoder resolution	500 [p/r]
Minimum Accuracy	0.18°

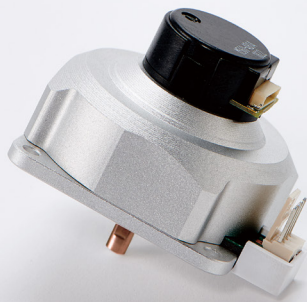
※PSM40 series will be made to order.

Motor for magnetic field environment

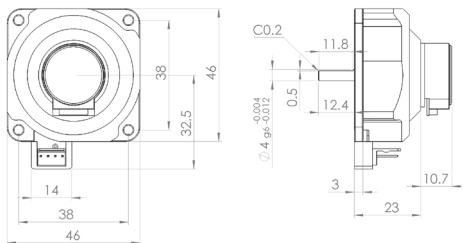
PSM40N SERIES

APPEARANCE / FEATURES

PSM40N-ET



Small motor with 1,000 p/r encoder for magnetic field environment.
Equipped with 1,000 pulse/trun TTL signals output encoder. Motor position and speed can be controlled with accuracy of $\pm 0.09^\circ$ (Multiplying by 4 times) in a magnetic field of 3 [T]. It is ideal as a motor for high-precision positioning stages used in MRI.



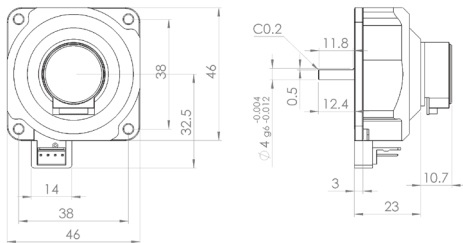
※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD $\Phi 28$ on the motor base side

Model Name	Motor with 1,000 p/r encoder	PSM40N-ET
Drive Frequency	52~58 [KHz]	
Drive Voltage	130 [Vrms]	
Rated Speed	150[rpm]	
Maximum Speed	250[rpm]	
Rated Torque	0.15 [N·m]	
Maximum Torque	0.3 [N·m]	
Holding Torque	0.3 [N·m]	
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)	
Temperature Range	-10 ~ +55 [°C]	
Life Time	3,000 [Hours]	
Size(W×D×H)	46×46×46 [mm]	
Weight	90[g]	
Encoder resolution	1,000 [p/r]	
Minimum Accuracy	0.09°	

PSM40N-ET2



Small motor with 2,000 p/r encoder for magnetic field environment.
Equipped with 2,000 pulse/turn TTL signals output encoder. Motor position and speed can be controlled with an accuracy of $\pm 0.045^\circ$ (Multiplying by 4 times) in a magnetic field of 3 [T]. It is ideal as a motor for ultra-high precision indexing equipment used in MRI.



※ There is a mounting screw hole with a depth of 3.5 mm with 3-M3 PCD $\Phi 28$ on the motor base side

Model Name	Motor with 2,000 p/r encoder	PSM40N-E2T
Drive Frequency	52~58 [KHz]	
Drive Voltage	130 [Vrms]	
Rated Speed	150[rpm]	
Maximum Speed	250[rpm]	
Rated Torque	0.15 [N·m]	
Maximum Torque	0.3 [N·m]	
Holding Torque	0.3 [N·m]	
Direction & Response	CW, CCW, Less than 1 [ms] (No-load)	
Temperature Range	-10 ~ +55 [°C]	
Life Time	3,000 [Hours]	
Size(W×D×H)	46×46×46 [mm]	
Weight	90[g]	
Encoder resolution	2,000[p/r]	
Minimum Accuracy	0.045°	

DESIGN

SPEC

※PSM40 series will be made to order.

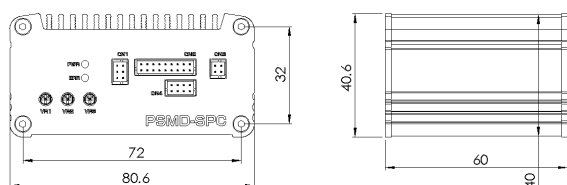
Motor Driver

PSMD SERIES

PSMD-SPC



This analog control model allows you to control the direction of motor rotation with two TTL signals and an analog voltage of 0 to 3.2[V].It can be used in combination with a motor with an encoder to stabilize the speed of the equipment.It is ideal for applications where an external analog voltage is used to control ultrasonic motors at a constant speed.



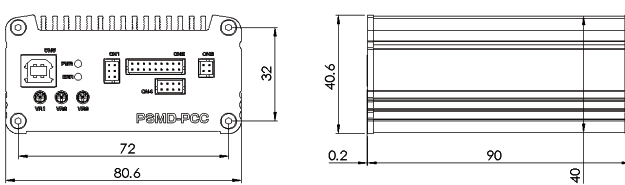
Model Name	Driver with speed stabilization function PSMD-SPC
Frequency / Wave Form	20 [KHz] ~ 55 [KHz] / Synthetic sine wave
Motor Drive Voltage	130 [Vrms] ~ 140 [Vrms]
Variable speed system	Analog voltage (DC 0 [V] ~ 3.2 [V])
No-load Speed Range	1 [rpm] ~ Maximum number of revolutions of the motor
Start-Stop Control	Switch to CW, CCW control terminal, Operation by external signal (active-low)
Starting Response	10 [ms] (No inertial load)
Stopping Response	Less than 1 [ms] (No inertial load)
Temperature Range	-10 [°C] ~ +60 [°C]
Power Supply	DC 24 [V] ± 0.5 [V] / Normal 1 [A], up to 2.5 [A]
Over Current Protection	Equipped with Resettable overcurrent protection circuit
Life Time	Operation 10,000 [Hours] or 1 year after shipment whichever is shorter
Size(W×D×H)	80 × 60 × 45 [mm]
Weight	250[g]
Remarks	With speed stabilization function

※ It is adjusted by the motor of the serial number and the pair at the time of shipment.
※ PSM60/40 S motor for general environment, PSM60/40 N Motor for magnetic field environment can be controlled in the same way.

PSMD-PCC



In addition to the functions of PSMD-SPC, this model enables digital control of the motor rotation direction and speed directly from a USB connected PC. To control a motor by a digital signal without inputting a TTL signal for rotation direction control or an analog voltage for speed control. Ideal for precise control of ultrasonic motors.



Model Name	High-precision control driver with USB connection PSMD-PCC
Frequency / Wave Form	20 [KHz] ~ 55 [KHz] / Synthetic sine wave
Motor Drive Voltage	130 [Vrms] ~ 140 [Vrms]
Variable speed system	Analog voltage (DC 0 [V] ~ 3.2 [V]) or Digital signal control from USB connected devices
No-load Speed Range	0.1 [rpm] ~ Maximum number of revolutions of the motor
Start-Stop Control	Operation by external signal (active-low) or Digital signal control from USB connected devices
Starting Response	10 [ms] (No inertial load)
Stopping Response	Less than 1 [ms] (No inertial load)
Temperature Range	-10 [°C] ~ +60 [°C]
Power Supply	DC 24 [V] ± 0.5 [V] / Normal 1 [A], up to 2.5 [A]
Over Current Protection	Equipped with Resettable overcurrent protection circuit
Life Time	Operation 10,000 [Hours] or 1 year after shipment whichever is shorter
Size(W×D×H)	80 × 90 × 45 [mm]
Weight	270[g]
Remarks	Can be operated by connecting to a PC via USB

※ It is adjusted by the motor of the serial number and the pair at the time of shipment.
※ PSM60/40 S motor for general environment, PSM60/40 N Motor for magnetic field environment can be controlled in the same way.

APPEARANCE / FEATURES

DESIGN

SPEC

Pin Assignment of the Driver

Each driver is equipped with a volume for adjustment (VR1-VR3) and various connectors (CN1-CN5) according to its characteristics

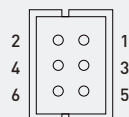
- VR1: Volume for minimum speed adjustment (PSMD-SPC only)
 VR2: Volume for maximum speed adjustment (PSMD-SPC only)
 VR3: CW and CCW speed balancing volume (PSMD-SPC only)

- CN1: Power connector (All Drivers)
 CN2: Connector for motor control signal (All Drivers)
 CN3: Connector for motor connection (All Drivers)

- CN4: Connector for encoder (All Drivers)
 CN5: Connector for PC connection (PSMD-PCC only)

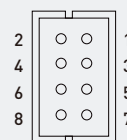
Be sure to check the information of each terminal before using.

CN1



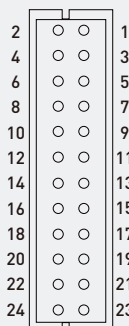
1. Main_power_input (+24V)
2. Main_power_input (+24V)
3. GND
4. GND
5. CASE
6. CASE

CN4



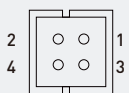
1. Voltage output for encoder (+5V) Red
2. GND Black
3. Encoder A phase (+) input Blue
4. Encoder A phase (-) input Green
5. Encoder B phase (+) input White
6. Encoder B-phase (-) input Gray
7. Encoder Z-phase (+) input Yellow
8. Encoder Z-phase (-) input Orange

CN2



1. Reference Output [3.3 V]
2. Speed specified voltage input
3. GND
4. Direction Control: CW
5. Direction Control: CCW
6. GND
7. SPI_CS input
8. SPI_CLK input
9. SPI_DT input
10. SPI_DT output
11. BOOST mode input
12. GND
13. PWM_code_02 input (Options)
14. PWM_code_01 input (Options)
15. PWM_code_00 input (Options)
16. PWM_SEL_input (Options)
17. ERROR_output
18. AUX_01_input (Options)
19. AUX_00_nput (Options)
20. GND
21. Phase_A[+]_output (Only when the encoder is connected)
22. Phase_B[+]_output (Only when the encoder is connected)
23. --
24. --

CN3



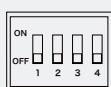
1. Sin signal output Red
2. Cos signal output White
3. FB signal input Yellow
4. GND Black

CN5



1. --
2. - Data
3. + Data
4. GND

SW1



- ⊙No encoder (No speed control)
 1: OFF, 2: OFF, 3: OFF, 4: OFF

- ⊙Single-mode encoder
- PSM60* - E
 1: ON, 2: OFF, 3: OFF, 4: OFF
 - PSM60* - ET
 1: ON, 2: OFF, 3: OFF, 4: ON
 - PSM60* - E2T
 1: ON, 2: OFF, 3: ON, 4: OFF

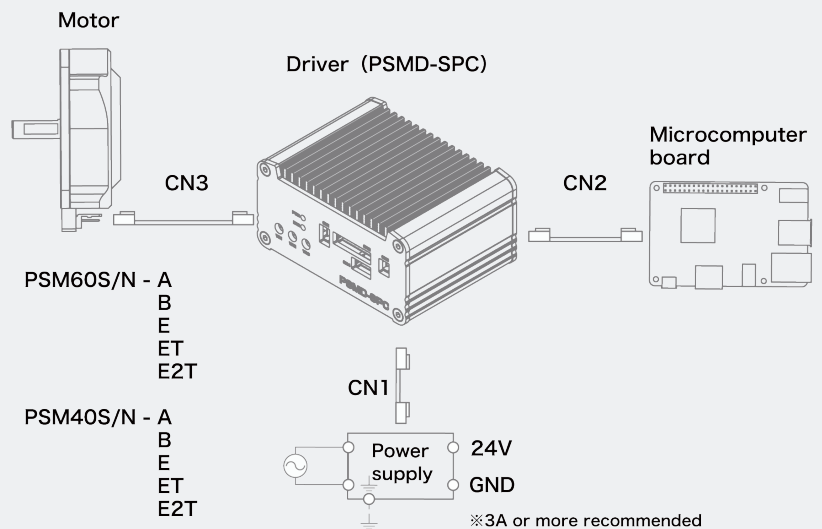
- ⊙Differential mode encoder
- PSM60* - E
 1: ON, 2: ON, 3: OFF, 4: OFF
 - PSM60* - ET
 1: ON, 2: ON, 3: OFF, 4: ON
 - PSM60* - E2T
 1: ON, 2: ON, 3: ON, 4: OFF
 - PSM60* - E36
 1: ON, 2: ON, 3: ON, 4: ON

How to connect the motor and the driver

PSMD-SPC[1]

No encoder signal, simple operation using the control board

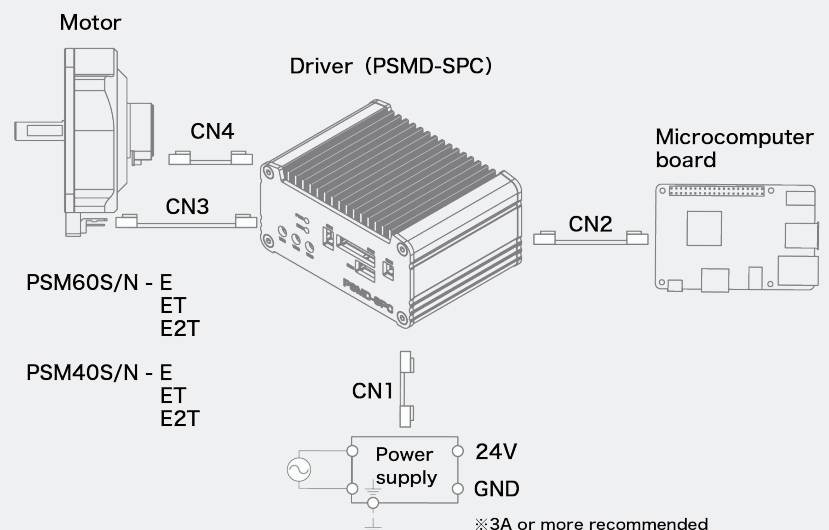
Enter the CN1 dc24v power supply, the TTL signal level signal (2: Active-Low), which controls the motor's rotational direction (CW/CCW) and stop state to CN2, and an analog signal of dc0v to 3.2 V for Speed change. Connect the CN3 to the signal input terminal of the motor. The signal required for motor control can be used for the port and analog voltage output of the microcomputer board, or it is possible to use the switch and the semi-fixed resistor. CN4 is not used because the motor has no encoder.



PSMD-SPC[2]

Speed control by encoder signal

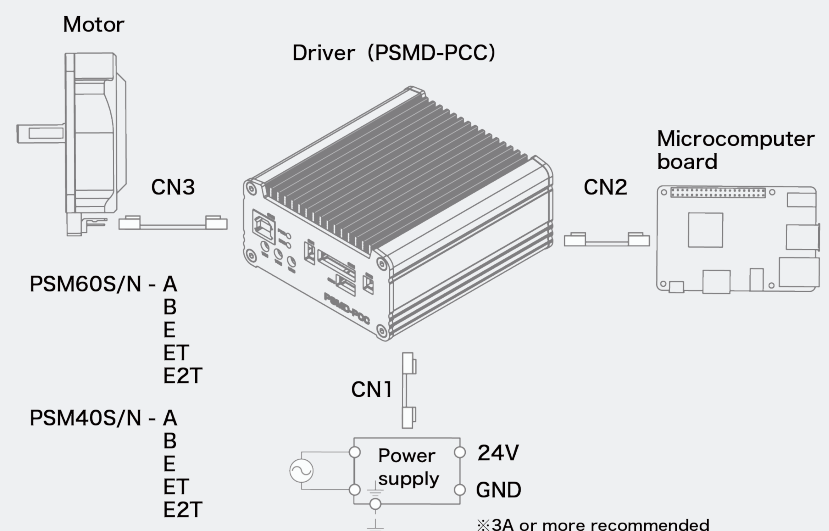
It is possible to maintain the speed of the motor by adding a constant voltage to the speed designation terminal without the speed control on the external microcomputer board by the speed stabilization function using the encoder signal. Enter the CN1 DC24 V power supply, the TTL signal level signal (2: Active-Low), which controls the motor's rotational direction (CW/CCW) and stop state to CN2, and an Analog signal of DC0 V to 3.2 V for Speed change. Connect the CN3 to the signal input terminal of the motor. Connect the CN4 to the encoder signal terminal of the motor.



PSMD-PCC[1]

No encoder signal, simple operation using the control board

The signals required for motor control are the microcomputer board port and Analog voltage output. Or, operation with a switch and a semi-fixed resistor is possible. Enter the CN1 DC24 V power supply, the TTL signal level signal (2: Active-Low), which controls the motor's rotational direction (CW/CCW) and stop state to CN2, and an Analog signal of DC0 V to 3.2 V for Speed change. Connect the CN3 to the signal input terminal of the motor. CN4 and CN5 are not connected.



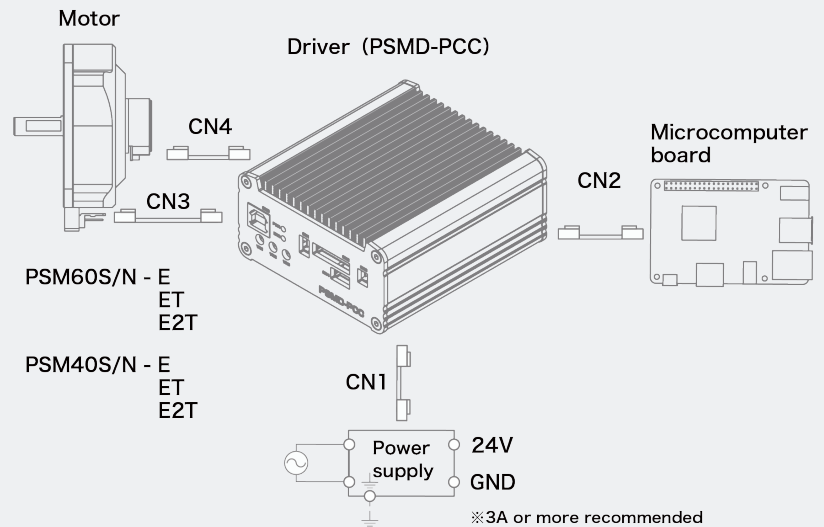
How to connect the motor and the driver

PSMD-PCC[2]

Speed control by encoder signal

It is possible to maintain the speed of the motor by adding a constant voltage to the speed designation terminal without the speed control on the external microcomputer board by the speed stabilization function using the encoder signal.

Enter the CN1 DC24 V power supply, the TTL signal level signal (2: Active-Low), which controls the motor's rotational direction (CW/CCW) and stop state to CN2, and an Analog signal of DC0 V to 3.2 V for Speed change. Connect the CN3 to the signal input terminal of the motor. Connect the CN4 to the encoder signal terminal of the motor. CN5 is not connected.

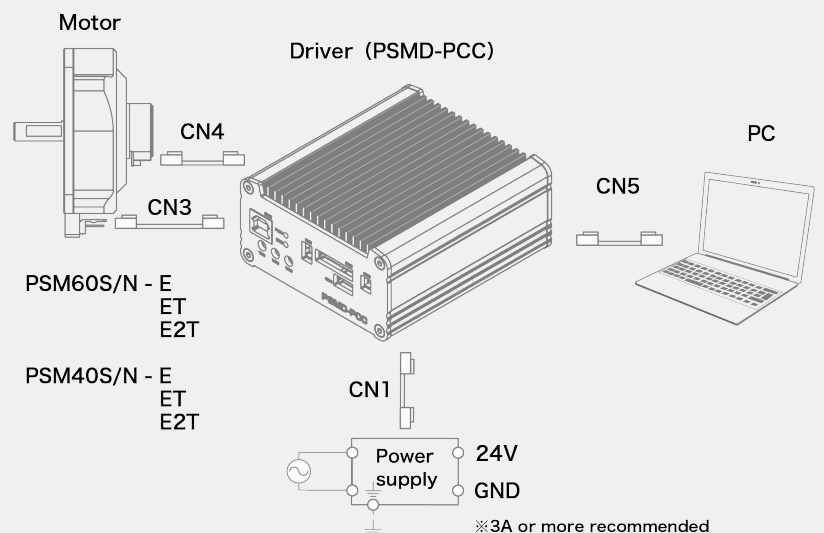


PSMD-PCC[3]

PC application control via USB connection

It is possible to control the rotation direction of the motor (CW/CCW), stop state, and control instructions for speed change via USB. Because the analog voltage control signal is not necessary, it is possible to operate the Ultrasonic Motor easily without the peripheral device such as a microcomputer board is prepared.

CN1 Connect DC24 V power. CN2 is not connected. Connect the CN3 to the signal input terminal of the motor. Connect the CN4 to the encoder signal terminal of the motor. Connect the CN5 to the USB terminal of the PC.

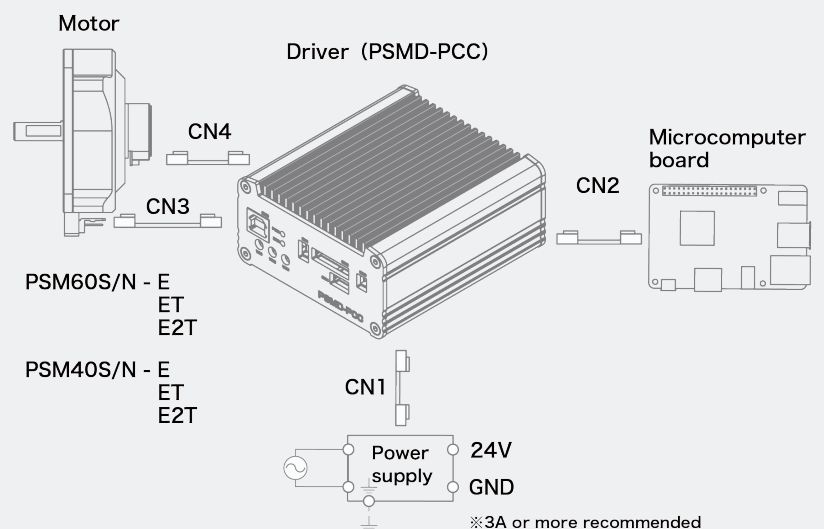


PSMD-PCC[4]

Motor Operation Using Microcontroller, Control Device and SPI Communication

CN1 is equipped with a 24VDC power supply, and CN2 is used to communicate with microcomputers and PLCs by the SPI method. Connect CN3 to the signal input terminal of the motor and CN4 to the encoder signal terminal of the motor. The CN5 is not used.

The direction and speed of the motor's rotation can be controlled by command, allowing you to use your existing system to operate the motor with digital signals.



Frequently Asked Questions

F A Q

Q Where can I buy a product?

- A** There are three ways to purchase our products.
1. Purchase from our affiliated trading company
 2. Online purchase on the web (Official Online Store, Yahoo! Shopping)
 3. Please contact us directly and purchase
- If you would like to receive a quantity discount, please contact us directly.

Q Please tell me how to order products.

- A** The order method is different depending on the method of purchase.
1. When purchasing from the website, please order the required quantity from the official online store or the Yahoo! shopping site. As soon as we confirm the information, we will inform you the delivery date.
 2. In case of direct purchase from us or our affiliated company, please ask for a quotation. If you request us directly, please use the email or contact form.

Q Can I order from one piece?

- A** All of our products can be purchased from one piece.

Q Which drivers should I choose?

- A** PSMD-SPC is recommended for analog motor control using a microcomputer, PLC, or external resistor. PSMD-PCC is recommended for digital control of the motor by USB connection or SPI communication from PC, microcomputer or PLC.

Q Is it possible to combine a motor and a driver with different serial numbers?

- A** PSMD-SPC and PSMD-PCC can be used because the setting can be changed according to the presence or absence of an encoder and the resolution by switching the switch. However, the speed stabilization function of the driver is not available when a motor without encoder (***- A/B) is used. If you are combining motors or drivers with different serial numbers, it is recommended to adjust the minimum and maximum speeds.

Q How are endurance times calculated?

- A** We consider the condition that the maximum torque has dropped to 60% against the characteristics at the time of shipment as the motor's life expectancy.

Q Can I use it in a vacuum environment?

- A** Our Ultrasonic Motor can operate even in a vacuum. However, in a vacuum environment, the condition of friction is deteriorated, so the life expectancy may be shortened. The operation is not guaranteed because it is different from the use in the general environment.

Q Is there anything special to pay attention to in the usage environment or storage environment?

- A** Because the Ultrasonic Motor rotates by using friction, it is necessary to avoid the state of the friction greatly changes. For example, please refrain from using it in water, high humidity, hot environment (humidity: 60% or more, temperature: 65 °c or higher).

Q What is the difference with DC motor etc.?

- A** When compared to a DC motor with the same torque, our Ultrasonic Motor is small in size from 1/5 to 1/10 times. The weight also becomes lighter along with it. The Ultrasonic Motor is very quiet sound even in operation. Even with non-energized / uncontrolled situations, our Ultrasonic Motor can maintain attitude and angle with electric power 0 by friction force.

Q What are the advantages of Ultrasonic Motors?

- A** Ultrasonic Motors are compatible with non-magnetic environments that can be used in small, high torque, static and magnetic fields. By turning an existing motor into our Ultrasonic Motor, you can expect to reduce the overall size and power consumption of the entire device. In addition, it can be positioned with high accuracy as a motor for transfer equipment used in MRI, semiconductor manufacturing equipment, and elemental analysis equipment.

Q What are the disadvantages of Ultrasonic Motors?

- A** Our Ultrasonic Motors life can compete with that of stepper motors. However, it is still shorter than the life of a DC motor.

Q How far can the motor and driver be separated?

- A** The standard cable length is 3m. Motor and driver can be separated up to 30m (limited to our genuine products).

Q Is it possible to custom order?

- A** We can customize one shaft length change and one diameter change. It is also possible to produce a complete custom motor. Please contact us by e-mail or contact form for custom specifications.



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